

## AMENDMENT TO THE CLAIMS

Replace the claims with the following rewritten version:

1. (Currently Amended) Hardware implemented filtering method comprising: ~~the steps of~~
  - establishing a representation (DIS) of ~~the~~a derivative of at least a part of a time-quantized input signal (IS), and
  - establishing at least one sample of a time- and amplitude-quantized output signal (OS) by performing filtering on the basis of at least a part of a filter representation (IFC1, IFC2, IFC3) and said representation (DIS) of the derivative of at least a part of said input signal (IS).
2. (Currently Amended) Hardware implemented method of convolving in ~~the~~a time domain an input signal ( $x[n]$ ) with an impulse response ( $h[k]$ ) in order to establish an output signal ( $y[n]$ ), comprising:
  - providing~~characterised by that~~ said output signal ( $y[n]$ ) ~~is provided~~ at least partly by a convolution in the time domain of a difference signal representation ( $x'[n]$ ) of said input signal ( $x[n]$ ) and a sum representation ( $l[k]$ ) of said impulse response ( $h[k]$ ).
3. (Currently Amended) Hardware implemented filtering method according to claim 1, whereby said ~~step of~~ establishing at least one sample of a time- and amplitude-quantized output signal (OS) is implemented according to the method of claim 2.
4. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 3~~2, whereby said impulse response is finite.
5. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 4~~, whereby said time-quantized input signal (IS) comprises in average at least 10, ~~preferably at least 64, and even more preferably at least 128~~ samples for each input signal value change.

6. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 5~~, whereby said time-quantized input signal (IS) is a pulse width modulated signal.

7. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 6~~, whereby said establishing a representation (DIS) of the derivative of at least a part of said time-quantized input signal (IS) comprises ~~the step of~~ establishing a sequence of differences between successive samples of said at least a part of said input signal (IS).

8. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 7~~, whereby said at least a part of said time-quantized input signal (IS) in respect of its length corresponds to the length of said at least a part of an impulse response.

9. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 8~~, whereby said representation (DIS) of the derivative of at least a part of said time-quantized input signal (IS) is stored in a differentiated input signal representing array (DA).

10. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 9~~, whereby said establishing a representation (DIS) of the derivative of at least a part of a time-quantized input signal (IS) comprises ~~the step of~~ indexing corresponding times and directions of amplitude changes of said at least a part of said input signal (IS).

11. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 10~~, whereby the length of said at least a part of said filter representation (IFC1, IFC2, IFC3) is an integer multiple of the length of a symbol of said at least a part of said time-quantized input signal (IS).

12. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 11~~, whereby ~~the~~ number of changes within a symbol of said at least a part of said time-quantized input signal is constant.

13. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 12~~, whereby said times are indexed relative to each other.

14. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 13~~, whereby said establishing a representation (DIS) of the derivative of at least a part of a time-quantized input signal (IS) comprises ~~the step of~~ storing into a snapshot register (SR) said at least a part of said time-quantized input signal (IS).

15. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 14~~, whereby said establishing a representation (DIS) of the derivative of at least a part of a time-quantized input signal (IS) comprises ~~the step of~~ querying said snapshot register (RS) regarding input signal changes.

16. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 15~~, whereby said at least a part of said filter representation (IFC1, IFC2, IFC3) is a sum representation of at least a part of an impulse response.

17. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 16~~, whereby said at least a part of said filter representation (IFC1, IFC2, IFC3) is predetermined.

18. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 17~~, whereby said at least a part of said filter representation (IFC1, IFC2, IFC3) is implemented by means of at least one filter coefficient, ~~more preferably at least 128 filter coefficients and even more preferably at least 384 filter coefficients.~~

19. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 18~~, whereby said at least a part of said filter representation (IFC1, IFC2,

IFC3) is implemented by means of at least one model, ~~preferably represented~~  
~~bycomprising~~ at least one polynomial.

20. (Currently Amended) Hardware implemented filtering method according to ~~any of~~  
~~the claims 1 to 19~~, whereby said implementation of said at least a part of said filter  
representation (IFC1, IFC2, IFC3) is adapted to utilize any symmetry of said filter  
representation.

21. (Currently Amended) Hardware implemented filtering method according to ~~any of~~  
~~the claims 1 to 20~~, whereby said at least a part of said filter representation (IFC1, IFC2,  
IFC3) is user-adjustable.

22. (Currently Amended) Hardware implemented filtering method according to ~~any of~~  
~~the claims 1 to 21~~, whereby said performing filtering comprises convolving said at least  
a part of said filter representation (IFC1, IFC2, IFC3) with said representation (DIS) of  
the derivative of at least a part of said time-quantized input signal (IS).

23. (Currently Amended) Hardware implemented filtering method according to ~~any of~~  
~~the claims 1 to 22~~, whereby said performing filtering further comprises for each of said  
at least one sample of a time- and amplitude-quantized output signal (OS) adding the  
result of multiplying an initial value (IV) of said at least a part of said time-quantized  
input signal (IS) with a value of said at least a part of said filter representation (IFC1,  
IFC2, IFC3).

24. (Currently Amended) Hardware implemented filtering method according to ~~any of~~  
~~the claims 1 to 23~~, whereby said performing filtering further comprises adding, for each  
of said at least one sample of a time- and amplitude-quantized output signal (OS), an  
initial value (IV) of said at least a part of said time-quantized input signal (IS).

25. (Currently Amended) Hardware implemented filtering method according to ~~any of~~  
~~the claims 1 to 24~~, whereby said performing filtering comprises exercising the

expression  $y[n] = \sum_{k=0}^{N-2} (l[k] \cdot x'[n-k]) + l[N-1] \cdot x[n-(N-1)]$ , where  $y[n]$  represents said at least one sample of a time- and amplitude-quantized output signal (OS),  $x[n]$  represents said at least a part of said time-quantized input signal (IS),  $x'[n]$  represents said representation (DIS) of the derivative of  $x[n]$ ,  $l[k]$  represents said at least a part of said filter representation (IFC1, IFC2, IFC3), and  $N$  represents the length of  $l[k]$ .

26. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 25~~, whereby said performing filtering further comprises performing conventional filtering.

27. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 26~~, whereby ~~the~~ sample rate of said time- and amplitude-quantized output signal (OS) is different from ~~the~~ sample rate of said time-quantized input signal (IS).

28. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 27~~, whereby ~~the~~ sample rate of said time- and amplitude-quantized output signal (OS) corresponds to ~~the~~ symbol rate of said time-quantized input signal (IS).

29. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 28~~22, whereby said convolving said at least a part of said filter representation (IFC1, IFC2, IFC3) with said representation (DIS) of the derivative of at least a part of said time-quantized input signal (IS) is performed for only some of the samples of said time-quantized input signal (IS), ~~preferably for only every 128<sup>th</sup> sample~~.

30. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 29~~, whereby said filter representation (IFC1, IFC2, IFC3) comprises a sum representation of a low-pass filter.

31. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 30~~, whereby said method is exercised in real time.

32. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 31~~, whereby said at least a part of a filter representation (IFC1, IFC2, IFC3) represents at least a part of an impulse response.

33. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 32~~, whereby said at least a part of a filter representation (IFC1, IFC2, IFC3) represents the derivative of at least a part of an impulse response.

34. (Currently Amended) Hardware implemented filtering method according to ~~any of the claims 1 to 33~~ further comprising the step of  
- integrating at least once said time- and amplitude-quantized output signal (OS).

35. (Currently Amended) Hardware implemented decimation method for decimating a time-quantized input signal (IS) comprising: ~~the steps of~~  
———dividing said time-quantized input signal (IS) into intervals,  
———for each of said intervals establishing a sample of a time- and amplitude-quantized output signal (OS) according to ~~any of the claims 1 to 34~~.

36. (Currently Amended) Fast filtering means (FFM) comprising:  
-differentiation means (DM) for establishing a representation (DIS) of ~~the~~ derivative of at least a part of a time-quantized input signal (IS), and  
-filtering means (FM) for establishing at least one sample of an output signal (OS) by performing filtering on the basis of at least a part of a filter representation (IFC1, IFC2, IFC3) and said representation (DIS) of the derivative of at least a part of said input signal (IS).

37. (Currently Amended) Fast filtering means (FFM) according to claim 36 ~~implementing~~configured to implement the hardware implemented filtering method according to ~~any of the claims 1 to 34~~ or the hardware implemented decimation method according to claim 35.